Painlevé-type reductions for the non-Abelian Volterra lattices

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Outline

Two non-Abelian (matrix) Volterra lattices

• VL¹
$$u_{n,x} = u_{n+1}u_n - u_nu_{n-1}$$
 (M.A. Salle, Theor. Math. Phys. 1982)

• VL²
$$u_{n,x} = u_{n+1}^{\mathrm{T}} u_n - u_n u_{n-1}^{\mathrm{T}}$$
 (new, arXiv:2010.09021)

 ${\it Results}$

• Substitutions
$$VL^1 \leftarrow \cdots \rightarrow VL^2$$

- Symmetries
- Lax pairs
- Higher symmetry + scaling $\rightarrow dP_1^i + P_4^i$
- Master-symmetry + scaling + $D_x \rightarrow dP_{34}^i + P_5^i$ i = 1, 2
- Master-symmetry $+ D_x \longrightarrow dP_{34}^i + P_3^i$

$VL^1 \leftarrow mVL^1 \leftarrow pot-mVL \rightarrow mVL^2 \rightarrow mVL^2$

The relation between VL^1 and mVL^2 is far from obvious.

$$\begin{aligned} & \mathrm{VL}^{1}: \quad u_{n,x} = u_{n+1}u_{n} - u_{n}u_{n-1} \\ & \mathrm{mVL}^{1}: \quad v_{n,x} = v_{n+1}(v_{n}^{2} - \alpha^{2}) - (v_{n}^{2} - \alpha^{2})v_{n-1} \qquad (\alpha \in \mathbb{C}) \\ & \mathrm{pot-mVL}: \quad w_{n,x} = (w_{n+1} + 2\alpha w_{n})(w_{n-1}^{-1}w_{n} + 2\alpha) \\ & \mathrm{mVL}^{2}: \quad v_{n,x} = (v_{n} - \alpha)v_{n+1}(v_{n} + \alpha) - (v_{n} + \alpha)v_{n-1}(v_{n} - \alpha) \\ & \mathrm{VL}^{2}: \quad u_{n,x} = u_{n+1}^{\mathrm{T}}u_{n} - u_{n}u_{n-1}^{\mathrm{T}} \end{aligned}$$

Substitutions:

$$\begin{split} \mathrm{VL}^1 &\leftarrow \mathrm{m}\mathrm{VL}^1: \quad u_n = (v_{n+1} + \alpha)(v_n - \alpha) &\quad \text{discrete Miura map} \\ \mathrm{m}\mathrm{VL}^1 &\leftarrow \mathrm{pot}\text{-}\mathrm{m}\mathrm{VL}: \quad v_n = w_{n+1}w_n^{-1} + \alpha \\ \mathrm{pot}\text{-}\mathrm{m}\mathrm{VL} \to \mathrm{m}\mathrm{VL}^2: \quad v_n = w_n^{-1}w_{n+1} + \alpha \\ \mathrm{m}\mathrm{VL}^2 \to \mathrm{VL}^2: \quad \begin{cases} u_n = (v_n + \alpha)(v_{n-1} + \alpha) &\text{for even } n \\ u_n = (v_n^{\mathrm{T}} - \alpha)(v_{n-1}^{\mathrm{T}} - \alpha) &\text{for odd } n \end{cases} \end{split}$$

Remark: an (incomplete) analogy with KdV

There is a sequence of substitutions

$$\mathrm{KdV} \xleftarrow{u=v^{2}\pm v_{x}+\alpha}{\mathrm{Miura\ map}} \mathrm{mKdV^{1}} \xleftarrow{v=w_{x}w^{-1}}{\mathrm{pot-mKdV}} \mathrm{pot-mKdV} \xrightarrow{v=w^{-1}w_{x}}{\mathrm{mKdV^{2}}}$$

between

$$\begin{split} \mathrm{KdV}: \quad & u_t = u_{xxx} - 3uu_x - 3u_xu\\ \mathrm{mKdV}^1: \quad & v_t = v_{xxx} - 3v^2v_x - 3v_xv^2 - 6\alpha v_x\\ \mathrm{pot-mKdV}: \quad & w_t = w_{xxx} - 3w_{xx}w^{-1}w_x - 6\alpha w_x\\ \mathrm{mKdV}^2: \quad & v_t = v_{xxx} + 3[v,v_{xx}] - 6vv_xv - 6\alpha v_x \end{split}$$

These equations can be obtained from the corresponding lattice equations by continuous limit, but no continuous analog of VL^2 is known.

Symmetries: basic derivations

- $D_x = D_{t_1}$, the lattice itself
- D_{t_2} , the simplest higher symmetry

VL¹:
$$u_{n,t_2} = (u_{n+2}u_{n+1} + u_{n+1}^2 + u_{n+1}u_n)u_n$$

 $- u_n(u_nu_{n-1} + u_{n-1}^2 + u_{n-1}u_{n-2})$
VL²: $u_{n,t_2} = (u_{n+1}^{\mathsf{T}}u_{n+2} + (u_{n+1}^{\mathsf{T}})^2 + u_nu_{n+1}^{\mathsf{T}})u_n$
 $- u_n(u_{n-1}^{\mathsf{T}}u_n + (u_{n-1}^{\mathsf{T}})^2 + u_{n-2}u_{n-1}^{\mathsf{T}})$

• D_{τ_1} , the classical scaling symmetry

$$u_{n,\tau_1} = u_n$$

• D_{τ_2} , the master-symmetry (nonlocal for VL¹, local for VL²)

VL¹:
$$u_{n,\tau_2} = (n + \frac{3}{2})u_{n+1}u_n + u_n^2 - (n - \frac{3}{2})u_nu_{n-1} + [s_n, u_n],$$

 $s_n - s_{n-1} = u_n$
VL²

VL²:
$$u_{n,\tau_2} = \left(n + \frac{3}{2}\right)u_{n+1}^{\mathrm{T}}u_n + u_n^2 - \left(n - \frac{3}{2}\right)u_n u_{n-1}^{\mathrm{T}}$$

Remark: associated systems

Due to the lattice, any variable u_{n+k} is an expression of u_n, u_{n+1} and their *x*-derivatives. Thence, any symmetry is equivalent to some coupled PDE system. It is a non-Abelian generalization of the Levi system (Levi, J. Phys. A 1981, Adler & Sokolov, arXiv: 2008.09174). The map $n \to n+1$ defines a Bäcklund transformation for this system.

For VL¹, the pair $(p,q) = (u_n, u_{n+1})$ satisfies, for any n, the system

$$\begin{cases} q_{t_2} = q_{xx} + 2q_xq + 2(qp)_x + 2[qp,q], \\ p_{t_2} = -p_{xx} + 2pp_x + 2(qp)_x + 2[qp,p]. \end{cases}$$

For VL², the pair $(p,q) = (u_n, u_{n+1}^{T})$ satisfies

$$\begin{cases} q_{t_2} = q_{xx} + 2q_xq + 2(pq)_x + 2[pq,q], \\ p_{t_2} = -p_{xx} + 2p_xp + 2(qp)_x + 2[p,qp] \end{cases}$$

Symmetries and constraints

In fact, there exists an infinite hierarchy of flows:

$$\begin{split} [D_{t_i}, D_{t_j}] &= 0, \quad [D_{\tau_i}, D_{t_j}] = j D_{t_{j+i-1}}, \\ [D_{\tau_i}, D_{\tau_j}] &= (j-i) D_{\tau_{j+i-1}}, \qquad i, j \geq 1. \end{split}$$

We only use symmetries that contain u_{n+k} with $|k| \leq 2$.

Any linear combination of derivations

$$D_t = \mu_1(xD_{t_2} + D_{\tau_2}) + \mu_2(xD_x + D_{\tau_1}) + \mu_3D_{t_2} + \mu_4D_x$$

commute with D_x . Therefore, the stationary equation

$$D_t(u_n) = 0$$

is a constraint consistent with the lattice.

Up to equivalence transformations, there are three different cases which lead to (non-Abelian) Painlevé equations:

$$\begin{array}{rcl} 2(xD_x + D_{\tau_1}) & +D_{t_2} & = 0 & \to & \mathrm{dP}_1 + \mathrm{P}_4 \\ xD_{t_2} + D_{\tau_2} & +\mu(xD_x + D_{\tau_1}) & & +\nu D_x = 0 & \to & \mathrm{dP}_{34} + \mathrm{P}_5 \\ xD_{t_2} + D_{\tau_2} & & & +\nu D_x = 0 & \to & \mathrm{dP}_{34} + \mathrm{P}_3 \end{array}$$

• In all cases, we start from some 5-point $O\Delta E$

$$f_n(u_{n-2}, u_{n-1}, u_n, u_{n+1}, u_{n+2}; x, \mu, \nu) = 0.$$

- It admits a reduction of order due to *partial* first integrals (pfi).
- The final result is a discrete Painlevé equation

$$g_n(u_{n-1}, u_n, u_{n+1}; x, \mu, \nu, \varepsilon, \delta) = 0.$$

- It defines a subclass of special solutions of the original equation. Additional constants $\varepsilon, \delta \in \mathbb{C}$ replace two matrix initial data.
- The x-dynamics is also consistent with pfi. The VL is reduced to an ODE system for (u_n, u_{n+1}) which is equivalent to a continuous Painlevé equation.

Scaling reduction: $D_{t_2} + 2(xD_x + D_{\tau_1}) = 0 \rightarrow dP_1 + P_4$

VL¹:
$$(u_{n+2}u_{n+1} + u_{n+1}^2 + u_{n+1}u_n)u_n - u_n(u_nu_{n-1} + u_{n-1}^2 + u_{n-1}u_{n-2})$$

+ $2x(u_{n+1}u_n - u_nu_{n-1}) + 2u_n = 0,$

VL²:
$$(u_{n+1}^{\mathsf{T}}u_{n+2} + (u_{n+1}^{\mathsf{T}})^2 + u_n u_{n+1}^{\mathsf{T}})u_n - u_n (u_{n-1}^{\mathsf{T}}u_n + (u_{n-1}^{\mathsf{T}})^2 + u_{n-2}u_{n-1}^{\mathsf{T}})$$

+ $2x(u_{n+1}^{\mathsf{T}}u_n - u_n u_{n-1}^{\mathsf{T}}) + 2u_n = 0.$

This can be represented as $F_{n+1}u_n - u_nF_{n-1} = 0.$

The equality $F_n = 0$ is pfi. Its consistency with D_x is due to identities:

•
$$F_{n,x} = (F_{n+1} - F_n)u_n + u_n(F_n - F_{n-1})$$
 for VL¹
• $F_{n,x} = (F_{n+1}^{T} + F_n)u_n - u_n(F_n + F_{n-1}^{T})$ for VL²

Two analogs of dP_1

$$u_{n+1}u_n + u_n^2 + u_n u_{n-1} + 2xu_n + \gamma_n = 0, \qquad dP_1^1$$

$$u_{n+1}^{\mathsf{T}} u_n + u_n^2 + u_n u_{n-1}^{\mathsf{T}} + 2xu_n + \gamma_n = 0, \qquad \mathrm{d} \mathbb{P}_1^2$$

$$\gamma_n := n - \nu + (-1)^n \varepsilon.$$

Continuous dynamics is as follows.

Two analogs of P_4

$$y'' = \frac{1}{2}y'y^{-1}y' + [\kappa_i y - \gamma y^{-1}, y'] + \frac{3}{2}y^3 + 4xy^2 + 2(x^2 - \alpha)y - 2\gamma^2 y^{-1}, \quad \mathbf{P}_4^i$$

where $\alpha = \gamma_{n-1} - \gamma_n/2 + 1$, $\gamma = \gamma_n/2$,

$$\kappa_1 = \frac{1}{2}$$
 and $\kappa_2 = -\frac{3}{2}$.

- In the scalar case, this reduction was introduced by Its, Kitaev and Fokas [Russ. Math. Surv. 1990, Comm. Math. Phys. 1991].
- Another non-Abelian version of dP₁ was studied by Cassatella-Contra, Mañas and Tempesta [Stud. Appl. Math. 2012, Nonlinearity 2018]:

$$u_{n+1} + u_n + u_{n-1} + 2x + \gamma_n u_n^{-1} = 0.$$

Master-symmetry reduction:

 $xD_{t_2} + D_{\tau_2} + \mu(xD_x + D_{\tau_1}) + \nu D_x = 0 \rightarrow dP_{34} + P_5 \text{ or } P_3$

The first step is easy (like in the previous case). It brings to 4-point equations

$$\begin{aligned} \mathrm{VL}^{1}: \ x(u_{n+2}u_{n+1}+u_{n+1}^{2}-u_{n}^{2}-u_{n}u_{n-1}) &-(2\mu x-n+\nu-\frac{3}{2})u_{n+1} \\ &+(2\mu x-n+\nu+\frac{1}{2})u_{n}-\mu+2(-1)^{n}\varepsilon=0, \end{aligned}$$
$$\mathrm{VL}^{2}: \ x\left(u_{n+1}^{\mathrm{T}}u_{n+2}+(u_{n+1}^{\mathrm{T}})^{2}-u_{n}^{2}-u_{n}u_{n-1}^{\mathrm{T}}\right) &-(2\mu x-n+\nu-\frac{3}{2})u_{n+1}^{\mathrm{T}} \\ &+(2\mu x-n+\nu+\frac{1}{2})u_{n}-\mu+2(-1)^{n}\varepsilon=0, \end{aligned}$$

where $\varepsilon \in \mathbb{C}$ is an integration constant. To obtain Painlevé equations, we need additional pfi.

In the scalar case, the above equation admits the integrating factor $xu_{n+1} + xu_n + n - \nu + \frac{1}{2}$ which brings to dP₃₄:

$$(z_{n+1}+z_n)(z_n+z_{n-1}) = 4x \frac{\mu z_n^2 + 2(-1)^n \varepsilon z_n + \delta}{z_n - n + \nu}, \quad z_n := 2xu_n + n - \nu$$

[Adler & Shabat, Theor. Math. Phys. 2019].

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Two analogs of dP_{34} for $\mu \neq 0$

$$(z_{n-1} + z_n)(z_n + (-1)^n \sigma + \omega)^{-1}(z_n + z_{n+1})$$

= $4\mu x(z_n - n + \nu)^{-1}(z_n + (-1)^n \sigma - \omega),$ dP¹₃₄

$$(z_{n-1}^{\mathrm{T}} + z_n)(z_n + (-1)^n (\sigma - \omega))^{-1} (z_n + z_{n+1}^{\mathrm{T}})$$

= $4\mu x(z_n - n + \nu)^{-1} (z_n + (-1)^n (\sigma + \omega))$ dP²₃₄

(where $\sigma = \varepsilon/\mu, \, \omega \in \mathbb{C}$).

Two analogs of $\mathrm{d}\mathbf{P}_{34}$ for $\mu=0$

$$\begin{cases} (z_{n+1}+z_n)(z_n-n+\nu)(z_n+z_{n-1}) = 4x(2\varepsilon z_n+\delta), & n=2k, \\ (z_n+z_{n-1})(z_{n+1}+z_n)(z_n-n+\nu) = 4x(-2\varepsilon z_n+\delta), & n=2k+1, \end{cases} d\widetilde{\mathbf{P}}_{34}^1$$

$$(z_{n+1}^{\mathrm{T}} + z_n)(z_n - n + \nu)(z_n + z_{n-1}^{\mathrm{T}}) = 4x(2(-1)^n \varepsilon z_n + \delta).$$
 $\mathrm{d}\widetilde{\mathrm{P}}_{34}^2$

Equations dP_{34}^i and $d\widetilde{P}_{34}^i$ are consistent with VL^{*i*}. This gives rize to ODE systems for the variables $(q, p) = (z_n, z_n + z_{n+1})$ or $(z_n, z_n + z_{n+1}^T)$.

Two analogs of P₅

$$dP_{34}^{1} \rightarrow \begin{cases} 2xq_{x} = p(q-n+\nu) - 4\mu x(q+\alpha)p^{-1}(q+\beta), \\ 2xp_{x} = pq + qp + p - p^{2} + 4\mu x(p-2q-\alpha-\beta), \end{cases} P_{5}^{1}$$
$$dP_{34}^{2} \rightarrow \begin{cases} 2xq_{x} = p(q-n+\nu) - 4\mu x(q+\alpha)p^{-1}(q+\beta), \\ 2xp_{x} = 2pq + p - p^{2} + 4\mu x(p-2q-\alpha-\beta) \end{cases} P_{5}^{2}$$

(in the scalar case, P_5 is satisfied by $y = 1 - 4\mu x p^{-1}$).

Two analogs of P₃

$$d\tilde{P}_{34}^{1} \rightarrow \begin{cases} 2xq_{x} = p(q-n+\nu) - 4xp^{-1}(2\varepsilon q+\delta), \\ 2xp_{x} = pq+qp+p-p^{2}-8\varepsilon x, \end{cases} (even n) \qquad P_{3}^{1} \\ d\tilde{P}_{34}^{2} \rightarrow \begin{cases} 2xq_{x} = p(q-n+\nu) - 4xp^{-1}(2(-1)^{n}\varepsilon q+\delta), \\ 2xp_{x} = 2pq+p-p^{2}-8(-1)^{n}\varepsilon x \end{cases} P_{3}^{2} \end{cases}$$

(in the scalar case, P₃ is satisfied by $y = p/(2\xi)$, $x = \xi^2$).

Zero curvature representations

$$VL^{1}: \quad u_{n,x} = u_{n+1}u_{n} - u_{n}u_{n-1} \quad \Leftrightarrow \quad L_{n,x} = U_{n+1}L_{n} - L_{n}U_{n}$$
$$L_{n} = \begin{pmatrix} \lambda & \lambda u_{n} \\ -1 & 0 \end{pmatrix}, \quad U_{n} = \begin{pmatrix} \lambda + u_{n} & \lambda u_{n} \\ -1 & u_{n-1} \end{pmatrix}$$

$$VL^{2}: \quad u_{n,x} = u_{n+1}^{\mathrm{T}} u_{n} - u_{n} u_{n-1}^{\mathrm{T}} \quad \Leftrightarrow \quad L_{n,x} = U_{n+1} L_{n} + L_{n} U_{n}^{\mathrm{T}}$$
$$L_{n} = \begin{pmatrix} 1 & -\lambda \\ 0 & \lambda u_{n} \end{pmatrix}, \quad U_{n} = \begin{pmatrix} \frac{1}{2}\lambda & 1 \\ -\lambda u_{n-1} & -\frac{1}{2}\lambda - u_{n-1} + u_{n}^{\mathrm{T}} \end{pmatrix}$$

These are the compatiblity conditions, respectively, for

$$\Psi_{n+1} = L_n \Psi_n, \qquad \Psi_{n,x} = U_n \Psi_n$$

or for

$$\Psi_{2n+1} = L_{2n} \Psi_{2n} \qquad \Psi_{2n,x} = -U_{2n}^{\mathsf{T}} \Psi_{2n},$$

= $L_{2n+1}^{\mathsf{T}} \Psi_{2n+2}, \qquad \Psi_{2n+1,x} = U_{2n+1} \Psi_{2n+1}.$

More generally, any derivation from $\rm VL^1/\rm VL^2$ hierarchy admits a representation of the form

 $L_{n,t} + \kappa L_{n,\lambda} = V_{n+1}L_n - L_n V_n \quad \text{or} \quad L_{n,t} + \kappa L_{n,\lambda} = V_{n+1}L_n + L_n V_n^{\mathrm{T}},$

with respective L_n and with certain V_n and $\kappa = \kappa(\lambda)$.

In both cases, we also have

$$U_{n,t} + \kappa U_{n,\lambda} = V_{n,x} + [V_n, U_n].$$

Therefore, for the stationary equation for D_t , we have the isomonodromic Lax pairs:

$$\kappa L_{n,\lambda} = V_{n+1}L_n - L_nV_n$$
 or $\kappa L_{n,\lambda} = V_{n+1}L_n + L_nV_n^{\mathsf{T}}$

for a discrete Painlevé equation and

$$\kappa U_{n,\lambda} = V_{n,x} + [V_n, U_n]$$

for a continuous one.

Explanation of dP_{34}^i partial first integral

Lemma. If
$$V_n = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$
 satisfies Lax equations

 $V_{n,x} = [U_n, V_n], \qquad V_{n+1}L_n = L_n V_n \quad \text{or} \quad V_{n+1}L_n = -L_n V_n^{\mathrm{T}}$

then its quasi-determinant $\Delta_n = b - ac^{-1}d$ is pfi.

Proof. It is easy to derive relations of the form

$$\Delta_{n,x} = f\Delta - \Delta g, \qquad \Delta_{n+1} = f\Delta_n g \quad \text{or} \quad \Delta_{n+1} = f\Delta_n^{\mathrm{T}} g$$

which imply that the constraint $\Delta = 0$ is preserved.

The constraint $xD_{t_2} + D_{\tau_2} + \mu(xD_x + D_{\tau_1}) + \nu D_x = 0$ admits the isomonodromic Lax pairs with $\kappa(\lambda) = \lambda^2 - 2\mu\lambda$. For $\lambda = 2\mu$, the matrix $V_n - \alpha I$ satisfies Lax equations and vanishing of its quasi-determinant gives exactly dP_{34}^i .